

AMENDMENTS TO THE SPECIFICATION:

Please replace the paragraph beginning at page 1, line 2, with the following rewritten paragraph:

--This invention is concerned with means for inserting objects being carried on a conveyor into cartons which move along with the conveyor. A standard mechanism for this purpose has a series of pushers which are moved across the conveyor to move objects into the respective cartons, the pushers then being carried around to the start end of the conveyor to locate on to further objects to be inserted. This mechanism has a large number of moving parts [[()]] in view of the fact that several independent moving pushers are employed[()] and occupies a substantial width to one side of the conveyor, for location of the pushers in their extended state.--

Please replace the paragraph beginning at page 2, line 1, with the following rewritten paragraph:

--With such an arrangement the pushers are moved by means of the control arm essentially diagonally across the track followed by the conveyor and are then brought back, along the same [[()]] diagonal[()] line, to the start position. Pushers are not carried around with the conveyor as in the previous mechanism.--

Please replace the paragraph beginning at page 2, line 27, with the following rewritten paragraph:

--The device shown in the drawings incorporates a conveyor 1 on which are carried [[[for example[()]]] individual food trays 2 which are to be inserted into open ended cartons 3. As the conveyor 1 moves [[[from right to left as shown in FIG. 1[()]]] the cartons 3 move at the same speed with the conveyor. A robotic support body 4 incorporates a control mechanism arranged to move the support body about suitable rotational axes so as to cause a control arm 5 to be moved across the conveyor 1. The arm 5 incorporates paddles 6 which engage with the trays 2 so as to push the trays towards the cartons 3. The arm 5 is moved across the conveyor 1, but at the same time moves from right to left at the same speed as for the conveyor 1. The diagonal path taken by a head 9 of the support body, carrying the arm 5, is indicated by the broken line 7 as shown in FIGS. 2 and 3. This results in the trays 2 being pushed fully home into the cartons 3. As seen in the drawings, conveyor 1 has upward projections 1' perpendicular to the length of conveyor 1, that define between them paths 1'' also perpendicular to the length of conveyor 1, along which paths the trays 2 are pushed by arm 5 into cartons 3. The arm 5 is then raised and the head 9 is brought back along the reciprocal path 8 [[[as shown in FIG. 4[()]]] until the arm returns to and is lowered into the start condition as shown in FIG. 1. The same

operation can then be employed to move another set of four trays
into a subsequent series of four cartons.--